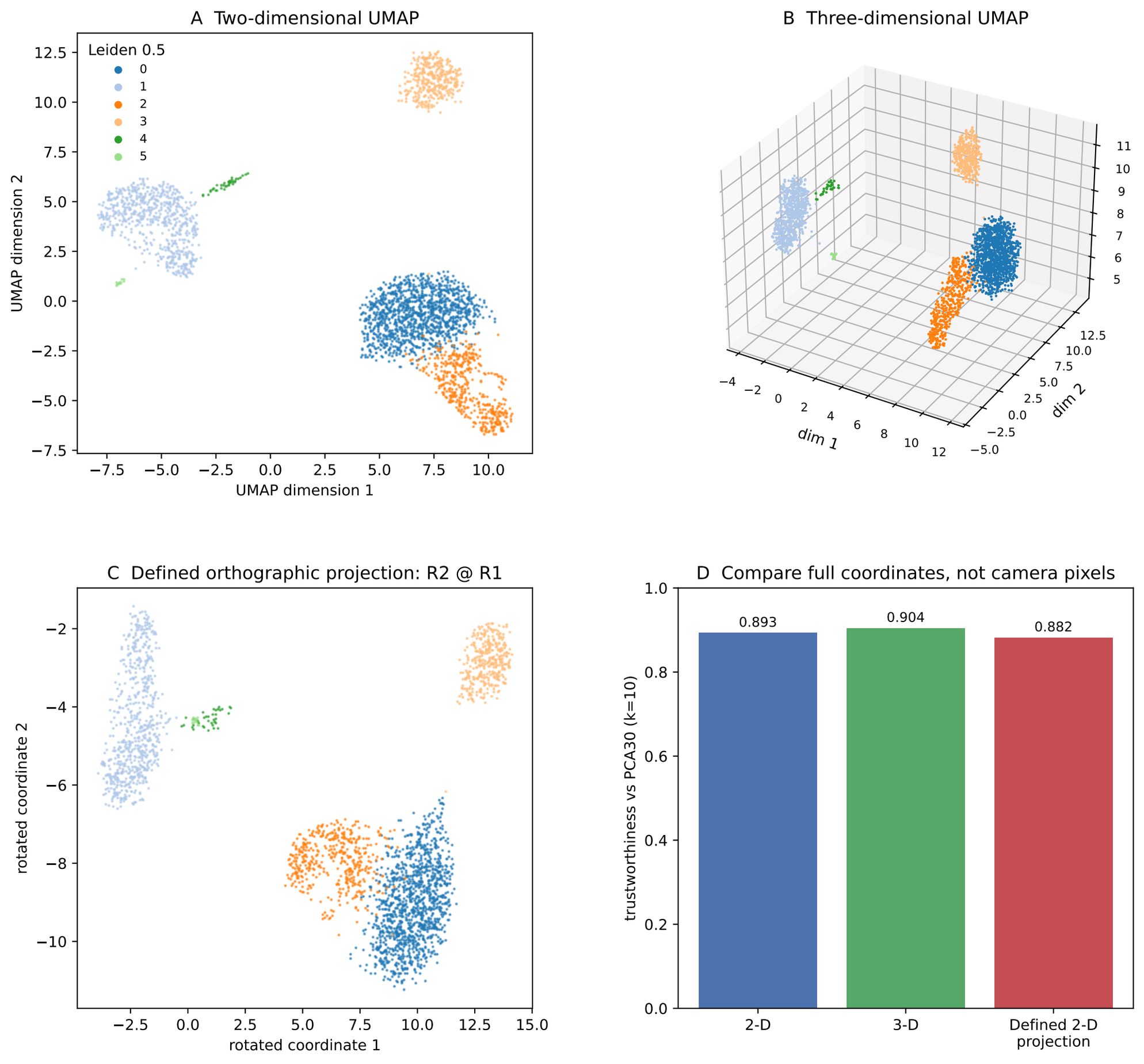
A Two-dimensional UMAP
Leiden 0.5
0
1
2
3
4
5
UMAP dimension 2
UMAP dimension 1
B Three-dimensional UMAP
dim 1
dim 2
C Defined orthographic projection: R2 @ R1
rotated coordinate 2
rotated coordinate 1
D Compare full coordinates, not camera pixels
trustworthiness vs PCA30 (k=10)
0.893
0.904
0.882
2-D
3-D
Defined 2-D projection